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Estratto dai
«Rendiconti del Seminario Matematico e Fisico di Milano»
Vol. LIII (1983)



TIPOGRAFIA FUSI - PAVIA

11/1986

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AN ABSTRACT MODEL FOR STRONG EVAPORATION

(Conferenza tenuta il 3 febbraio 1983)

SUNTO. — Si presenta una teoria astratta per problemi stazionari unidimensionali per il semispazio. Sulla base di questa teoria vengono provati alcuni risultati di esistenza e non esistenza già noti per modelli di evaporazione.

I. - INTRODUCTION.

In the past few years Arthur and Cercignani [1] and Siewert and Thomas [2, 3] have analyzed kinetic equations obtained by linearizing a BGK model equation about a drift Maxwellian. Let us denote the drift velocity (in suitable units) by $d > 0$. If one neglects transverse effects, one finds for the deviation $f(x, c)$ from the drift Maxwellian the equation (cf. [1, 2])

$$(1) \quad (c + d) \frac{\partial f}{\partial x}(x, c) + f(x, c) = \\ = \pi^{-1/2} \int_{-\infty}^{\infty} \left\{ 1 + 2cc' + 2 \left(c^2 - \frac{1}{2} \right) \left(c'^2 - \frac{1}{2} \right) \right\} e^{-c'^2} f(x, c') dc'.$$

If both longitudinal and transverse effects are incorporated, one finds the coupled system of equations (cf. [3])

$$(2) \quad (c + d) \frac{\partial}{\partial x} \begin{bmatrix} f_+(x, c) \\ f_-(x, c) \end{bmatrix} + \begin{bmatrix} f_+(x, c) \\ f_-(x, c) \end{bmatrix} = \\ = \pi^{-1/2} \int_{-\infty}^{\infty} \begin{bmatrix} 1 + 2cc' + \frac{2}{3} \left(c^2 - \frac{1}{2} \right) \left(c'^2 - \frac{1}{2} \right) & \frac{2}{3} \left(c^2 - \frac{1}{2} \right) \\ \frac{2}{3} \left(c'^2 - \frac{1}{2} \right) & \frac{2}{3} \end{bmatrix}$$

$$\times \begin{bmatrix} f_-(x, c') \\ f_+(x, c') \end{bmatrix} e^{-c'^2} dc'.$$

The velocity c runs from $-\infty$ to ∞ and the position variable x from 0 to ∞ . The boundary conditions to Eq. (1) are of the type

$$(3) \quad f(0, c) = \varphi(c) \quad (c > -d), \quad \lim_{x \rightarrow \infty} f(x, c) = 0.$$

On Eq. (2) one imposes the analogous boundary conditions

$$(4) \quad \begin{bmatrix} f_+(0, c) \\ f_-(0, c) \end{bmatrix} = \begin{bmatrix} \varphi_+(c) \\ \varphi_-(c) \end{bmatrix} \quad (c > -d), \quad \lim_{x \rightarrow \infty} \begin{bmatrix} f_+(x, c) \\ f_-(x, c) \end{bmatrix} = 0.$$

The functions φ , φ_+ and φ_- are of a special type (namely, collision invariants).

In order to apply Hilbert space methods to the above boundary value problems we introduce the Hilbert space $L_2(\mathbb{R}, d\sigma)$ of square integrable functions $h, k : \mathbb{R} \rightarrow \mathbb{C}$ with inner product

$$(5) \quad (h, k) = \int_{-\infty}^{\infty} h(c) \overline{k(c)} d\sigma(c), \quad \frac{d\sigma}{dc} = \pi^{-1/2} e^{-c^2}.$$

The boundary value problem (1)-(3) can now be reformulated as the vector-valued differential equation.

$$(6) \quad (Tf)'(x) = -Af(x), \quad 0 < x < \infty$$

$$(7) \quad Q_+ f(0) = \varphi, \quad \lim_{x \rightarrow \infty} \|f(x)\| = 0$$

on $L_2(\mathbb{R}, d\sigma)$, where T , A and Q_+ are defined by

$$(Th)(c) = (c + d)h(c), \quad (Ah)(c) = h(c) -$$

$$-\pi^{-1/2} \int_{-\infty}^{\infty} \left\{ 1 + 2cc' + 2 \left(c^2 - \frac{1}{2} \right) \left(c'^2 - \frac{1}{2} \right) \right\} e^{-c'^2} h(c') dc'$$

$$(Q_+ h)(c) = h(c) \quad (c > -d), \quad (Q_+ h)(c) = 0 \quad (c < -d).$$

The boundary value problem (2)-(4) can also be restated as Eqs. (6)-(7), but now the relevant Hilbert space is $L_2(\mathbb{R}, d\sigma) \oplus L_2(\mathbb{R}, d\sigma)$ and T , A and Q_+ are given by

$$(Th)(c) = (c + d)h(c),$$

$$(Ah)(c) = h(c) -$$

$$-\pi^{-1/2} \int_{-\infty}^{\infty} \begin{bmatrix} 1 + 2cc' + \frac{2}{3}\left(c^2 - \frac{1}{2}\right)\left(c'^2 - \frac{1}{2}\right) & \frac{2}{3}\left(c^2 - \frac{1}{2}\right) \\ \frac{2}{3}\left(c'^2 - \frac{1}{2}\right) & \frac{2}{3} \end{bmatrix} h(c') e^{-c'^2} dc'$$

$$(Q_+ h)(c) = h(c) \quad (c > -d), \quad (Q_+ h)(c) = 0 \quad (c < -d),$$

where $h = (h_+, h_-)$ is a column vector.

Abstract boundary value problems of the form (6)-(7) have been investigated intensively since the rigorous study by Hangelbroek [4] of the neutron transport equation below criticality. Concrete as well as abstract versions abound. Beals [5] and Van der Mee [6] studies Eqs. (6)-(7) on the abstract Hilbert space H , where T is a bounded injective self-adjoint and A a positive bounded self-adjoint operator with closed range, while Q_+ is the orthogonal projection of H onto the maximal positive T -invariant subspace. Further studies were done in [7, 8, 9] for unbounded A and in [5, 9] for unbounded T . Recently the results of [6, 8] were extended in [10] to non-positive A .

In [1, 2, 3] results on the existence and non-existence of solutions of the strong evaporation problems (1)-(3) and (2)-(4) were obtained only after considerable calculations, where φ was assumed to be an arbitrary vector in Q_+ [$\text{Ker } A$] (see Section III). There appeared to be a critical drift velocity d_M , corresponding to the speed of sound of the vapor, with the following properties:

- (a) for $d \geq d_M$ there do not exist non-trivial solutions;
- (b) for $0 < d < d_M$ there exist unique values of density and temperature (and transverse momenta for the vector equation) at $x = 0$ for which a solution exists.

For $d \geq d_M$ the non-existence of stationary non-trivial solutions has to do with the onset of turbulence at Mach one (i.e., $d = d_M$). For problem (1)-(3) it was found that $d_M = \sqrt{\frac{3}{2}}$ (see [1, 2]), whereas $d_M = \sqrt{\frac{5}{6}}$ was found in problem (2)-(4). In the present article we shall avoid these calculations by deriving these results from the ab-

stract theory of [5] and [8]. We shall not give detailed proofs but instead refer for details to the future paper [11].

II. - ABSTRACT HALF-SPACE MODELS.

Let us solve the abstract half-space problem (6)-(7), where T is a (possibly unbounded) self-adjoint operator with zero null space, A a bounded positive operator with finite-dimensional null space and Q_+ the orthogonal projection onto the maximal positive T -invariant subspace. Let us assume $\text{Ker } A = \{0\}$ first. Then the hypotheses of [5] are fulfilled and the operator $A^{-1}T$ is self-adjoint with respect to the Hangelbroek inner product (cf. [4])

$$(h, k)_A = (Ah, k); \quad h, k \in H.$$

Following Beals [5] we define H_T as the completion of the domain $D(T)$ of T with respect to the inner product

$$(8) \quad (h, k)_T = (|T|h, k),$$

and H_K as the completion of the domain $D(A^{-1}T) = D(T)$ of $A^{-1}T$ with respect to the inner product

$$(9) \quad (h, k)_K = (|A^{-1}T|h, k)_A = (A|A^{-1}T|h, k).$$

It can be shown (see [5]) that the inner products (8) and (9) are equivalent on $D(T)$. We may thus identify the completions H_T and H_K . We immediately see that Q_+ leaves invariant $D(T)$ and that the restriction of Q_+ to $D(T)$ extends to an orthogonal projection in H_T . Similarly, let P_+ be the $(\cdot, \cdot)_A$ -orthogonal projection of H onto the maximal $(\cdot, \cdot)_A$ -positive $A^{-1}T$ -invariant subspace. Then P_+ leaves invariant $D(A^{-1}T)$ and the restriction of P_+ to $D(A^{-1}T)$ extends to an orthogonal projection in H_K . Now exploit that $H_T = H_K$. As Beals [5] has shown, the operator

$$V = Q_+ P_+ + (I - Q_+) (I - P_+)$$

is well-defined and invertible on $H_T = H_K$. The inverse

$$E = V^{-1} : H_T \rightarrow H_T$$

now maps $Q_+ [H_T]$ onto $P_+ [H_T]$ and the solution of Eqs. (6)-(7) is unique and has the form

$$(10) \quad f(x) = e^{-xT^{-1}A} E\varphi, \quad 0 < x < \infty.$$

The semigroup in this expression is well-defined, since $E\varphi \in P_+[H_T]$. One thus obtains solutions in the extension space H_T of $D(T)$, whenever $\varphi \in D(T)$.

As we shall see, the problems (1)-(3) and (2)-(4) give rise to complications stemming from the non-triviality of $\text{Ker } A$. Under a minor regularity assumption on T and A (see [9]), the zero root linear manifolds

$$Z_0(T^{-1}A) = \bigcap_{n=0}^{\infty} \text{Ker}(T^{-1}A)^n, \quad Z_0(AT^{-1}) = \bigcap_{n=0}^{\infty} \text{Ker}(AT^{-1})^n$$

have the decomposition properties

$$(11) \quad Z_0(T^{-1}A) \oplus Z_0(AT^{-1})^\perp = H$$

$$(12) \quad Z_0(AT^{-1}) \oplus Z_0(T^{-1}A)^\perp = H,$$

where the orthogonal complement refers to the original inner product of H (see [9]). One observes that T is an invertible operator from the finite-dimensional space $Z_0(T^{-1}A)$ onto $Z_0(AT^{-1})$, while A is an invertible operator from $Z_0(AT^{-1})^\perp$ onto $Z_0(T^{-1}A)^\perp$. If one chooses an invertible operator β on $Z_0(T^{-1}A)$ such that

$$(T\beta h, h) \geq 0, \quad h \in Z_0(T^{-1}A),$$

then the linear operator A_β on H defined by

$$(13) \quad A_\beta h = \begin{cases} T\beta^{-1}h, & h \in Z_0(T^{-1}A) \\ Ah, & h \in Z_0(AT^{-1})^\perp, \end{cases}$$

is strictly positive self-adjoint on H , while

$$A_\beta^{-1}T = \beta \oplus (T^{-1}A|_{Z_0(AT^{-1})^\perp})^{-1}.$$

The use of β does not change the non-zero spectrum of $T^{-1}A$, but replaces the zero part by the eigenvalues of a non-singular matrix β .

Next we use the operator A_β to reduce Eqs. (6)-(7) to two sub-problems. Write $f = f_0 + f_1$ for the solution, where f_0 has its values in $Z_0(T^{-1}A)$ and f_1 in $Z_0(AT^{-1})^\perp$. Then Eqs. (6)-(7) decompose as follows:

$$(14) \quad (Tf_0)'(x) = -Af_0(x) \quad (0 < x < \infty)$$

$$(15) \quad (Tf_1)'(x) = -Af_1(x) \quad (0 < x < \infty),$$

where $\|f_1(x)\| \rightarrow 0$ for $x \rightarrow \infty$. Now consider the dummy equation

$$(16) \quad (Tg_0)'(x) = -A_\beta g_0(x) \quad (0 < x < \infty).$$

Also notice that A_β and A coincide on $Z_0(AT^{-1})$ (cf. Eq. (13)), which implies

$$(17) \quad (Tf_1)'(x) = -A_\beta f_1(x) \quad (0 < x < \infty).$$

Write $g = g_0 + f_1$; then Eqs. (16) and (17) can be summarized as

$$(18) \quad (Tg)'(x) = -A_\beta g(x) \quad (0 < x < \infty),$$

where A_β is strictly positive self-adjoint on H . Invoking Beals' result [5], there exists an invertible operator E_β on H_T , which maps $Q_+[H_T]$ onto $P_+[H_T]$ with P_+ the $(\cdot, \cdot)_{A_\beta}$ -orthogonal projection of $H_K (= H_T)$ onto the maximal $(\cdot, \cdot)_{A_\beta}$ -positive A_β^{-1} T -invariant subspace. The solution of Eq. (18) which vanishes for $x \rightarrow \infty$ generally has the form

$$g(x) = e^{-\sigma T^{-1} A_\beta} g(0), \quad 0 < x < \infty,$$

where $g(0) \in P_+[H_T]$. Because $Z_0(T^{-1}A)$ has a finite dimension, Eq. (14) has the general solution

$$f_0(x) = e^{-\sigma T^{-1} A} f_0(0) = \sum_{n=0}^{\infty} \frac{(-x)^n}{n!} (T^{-1}A)^n f_0(0).$$

Hence, solutions of Eqs. (6)-(7) all have the property $f_0(0) = 0$ and the form

$$(19) \quad f(x) = e^{-\sigma T^{-1} A} f(0) \quad (0 < x < \infty),$$

where $f(0) \in PP_+[H_T]$ and P is the projection of H onto $Z_0(AT^{-1})^\perp$ along $Z_0(T^{-1}A)$ (continuously extended to H_T). If one only requires that $\|f(x)\| = o(1)$ ($x \rightarrow \infty$), then $f_0(x) \equiv f_0(0)$ and

$$(20) \quad f(x) = e^{-\sigma T^{-1} A} g(0) + f_0(0) \quad (0 < x < \infty),$$

where $g(0) \in PP_+[H_T]$ and $f_0(0) \in \text{Ker } A$.

Formulas (19) and (20) represent general solutions only. As a final step we have to fulfill the half-range boundary condition $Q_+ f(0) = \varphi$ in Eq. (7), which gives the necessary and sufficient condition

$$(21) \quad \varphi \in PP_+[H_T] + (I - Q_+) [H_T]$$

for the existence of solutions of Eqs. (6)-(7). Because $PP_+[H_T]$ and $(I - Q_+) [H_T]$ have zero intersection, such solutions must be unique. Using the invertibility of E_β on H_T one may reduce condition (21) to an analysis on the finite-dimensional space $\text{Ker } A$. This we shall treat in detail in [11]. Here we state the main result:

THEOREM. - Let us choose a basis x_1, \dots, x_l of $\text{Ker } A$ of vectors satisfying $(Tx_i, x_j) = 0$ for $i \neq j$. Among the l numbers (Tx_k, x_k) let m_+ , m_0 and m_- the number of positive, zero and negative ones. Then

(i) Eqs. (6)-(7) have at most one solution, but the linear set of all $\varphi \in Q_+[H_T]$ for which a solution exists has codimension $m_+ + m_0$ in $Q_+[H_T]$.

(ii) Eq. (6) with boundary conditions

$$(22) \quad Q_+ f(0) = \varphi, \|f(x)\| = 0(1) \quad (x \rightarrow \infty)$$

has at least one solution for every $\varphi \in Q_+[H_T]$, but the linear set of all solutions of Eqs. (6)-(22) with $\varphi = 0$ has dimension m_- . Thus Eqs. (6)-(7) have measure of non-completeness $m_+ + m_0$ and solutions are unique. On the contrary, Eqs. (6)-(22) have measure of non-uniqueness m_- and solutions always exist. For $\text{Ker } A = \{0\}$ one finds $m_+ = m_0 = m_- = 0$ and Eqs. (6)-(7) and Eqs. (6)-(22) both are uniquely solvable. For non-positive A an analogous but more complicated theorem holds true (see [10]).

III. - APPLICATION TO STRONG EVAPORATION.

Let us apply the theorem to Eqs. (1)-(3). One easily computes (see [11]; cf. [1, 2]) that

$$\text{Ker } A = \left\{ \Delta \varrho + 2c(d_0 - d) + \left(c^2 - \frac{1}{2} \right) \Delta T / \Delta \varrho, d_0, \Delta T \text{ arbitrary} \right\}.$$

As the basis of Ker A appearing in the theorem we take

$$x_1(c) = 1, \quad x_2(c) = c, \quad x_3(c) = dc - c^2.$$

The $l=3$ numbers $(Tx_k, x_k) = \int_{-\infty}^{\infty} c|x_k(c)|^2 d\sigma(c)$ appear to be

$$(Tx_1, x_1) = d, \quad (Tx_2, x_2) = \frac{1}{2}d, \quad (Tx_3, x_3) = \frac{1}{2}d \left(d^2 - \frac{3}{2} \right).$$

Hence,

$$m_+ = 2, \quad m_0 = 0, \quad m_- = 1 \quad \text{for } 0 < d < \sqrt{\frac{3}{2}}$$

$$m_+ = 2, \quad m_0 = 1, \quad m_- = 0 \quad \text{for } d = \sqrt{\frac{3}{2}}$$

$$m_+ = 3, \quad m_0 = 0, \quad m_- = 0 \quad \text{for } d > \sqrt{\frac{3}{2}}.$$

Thus $m_+ + m_0 = 2$ for $0 < d < d_M$ and $m_+ + m_0 = 3$ for $d \geq d_M$ (with $d_M^2 = \frac{3}{2}$), which are the measures of non-completeness for the solution of Eqs. (1)-(3). Because of conservation laws one usually imposes two constraints to the solution and chooses $\varphi \in Q_+[\text{Ker } A]$. For all drift speeds $0 < d < d_M$ there exist unique $\Delta\varrho$ and ΔT to every d_0 , for which Eqs. (6)-(7) with boundary value function

$$(23) \quad \varphi(c) = \Delta\varrho + 2c(d_0 - d) + \left(c^2 - \frac{1}{2} \right) \Delta T, \quad c > -d$$

have a (unique) solution. For $d \geq d_M$ there are no non-trivial solutions to Eqs. (6)-(7), where φ is given by Eq. (23). An analogous result holds for Eqs. (2)-(4), but now $d_M = \sqrt{5/6}$. We thus recovered the main results of [1, 2, 3] from an abstract theory of half-range boundary value problems without substantial calculation.

ACKNOWLEDGEMENT. — This research represents a collaboration with Prof. W. Greenberg of Virginia Polytechnic Institute and State University, and was conducted while he and the author were visiting the Mathematics Institute of the University of Florence, Italy. The work was supported in part by D.O.E. grant no. DE-AS05 80ER10711. The author is indebted to C. Cercignani for a useful discussion.

SUMMARY. — An abstract theory of one-dimensional stationary half-space problems is presented. On the basis of this theory some previously known existence and nonexistence results for evaporation models are proved.

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